CE 530 Molecular Simulation

Lecture 19 Free-energy calculations: Distribution functions, precision and accuracy

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Review

- O All useful free-energy methods compute free-energy differences
- O Several approaches have been developed
- O FEP gives free-energy difference via an ensemble average
 - Asymmetric

Deletion method is awful

- O Four approaches to basic multistaging
 - Umbrella sampling, Bennett's method, staged insertion/deletion
- O Thermodynamic integration uses $dA/d\lambda = \langle dU/d\lambda \rangle$
 - Symmetric
- O Parameter hopping treats perturbation variable as an extension of phase space
 - *time spent at different values relates to their free-energy difference*

Free-Energy Perturbation

- O Each stage of a FEP method should be used only for "encompassing systems"
 - important configurations of one system form a subset of the configurations that are important to the other
 - staging may be needed to bring this about
- O The superset will have a higher entropy
 - use "H" and "L" to distinguish highand low-entropy systems
- O Remember hard-sphere with test particle
 - Every configuration of non-overlap is important to the N+1 particle (L) system
 - But every one of these configurations is of uniform importance in the N-particle (H) system





Distribution Functions

• The FEP average can be cast as a simple one-dimensional integral

$$e^{-\beta(A_L - A_H)} = \frac{\Lambda^{3N}}{Q_H} \int d\mathbf{r}^N e^{-\beta(U_L - U_H)} e^{-\beta U_H}$$
$$= \int du \, e^{-\beta u} \int d\mathbf{r}^N \delta \left(u - (U_L - U_H) \right) \frac{\Lambda^{3N} e^{-\beta U_H}}{Q_H}$$
$$e^{-\beta \Delta A} = \int du \, e^{-\beta u} \, p_H(u) \quad \text{reference is the high-entropy system}$$

O Likewise

 $e^{+\beta\Delta A} = \int du \, e^{+\beta u} p_L(u)$ ref

reference is the low-entropy system

O Energy distributions $p_H(u) = \langle \delta(u - \Delta U) \rangle_H$ normalized $p_L(u) = \langle \delta(u - \Delta U) \rangle_L$ normalized NomenclatureFree-energy difference: $\Delta A \equiv A_L - A_H$ Entropy difference: $\Delta S \equiv S_L - S_H < 0$ Energy difference: $u \equiv U_L(\mathbf{r}^{(N)}) - U_H(\mathbf{r}^{(N)})$

Interpretation

- O Consider in the context of particle insertion (ghost \rightarrow real)
- O High-S system is ghost, Low-S is real
- O u is the difference in energy U_{real} U_{ghost}
- O p_H is the distribution of energies (virtual energy changes) experienced by molecule acting as a ghost (insertion energy)
 - many overlaps, so energy will tend to be large
- O p_L is the distribution of energies experienced by a molecule interacting with the others (deletion energy)
 - no overlap, favorable interactions, so energy will be small

O Typical behaviors -



Generalized Insertion and Deletion

- Widom insertion samples high-S system, perturbs to low-S system
- O Widom deletion does the opposite
- O Define
 - Generalized insertion: *FEP* calculation in which high-entropy system governs sampling
 - Generalized deletion: *FEP* calculation in which low-entropy system governs sampling





O Previously we derived this result

$$\langle M \rangle_L = \frac{\left\langle M e^{-\beta(U_L - U_H)} \right\rangle_H}{\left\langle e^{-\beta(U_L - U_H)} \right\rangle_H}$$

Non-Boltzmann averaging formula (used 0 and W to designate systems)

O Previously we derived this result

$$\langle M \rangle_L = \frac{\left\langle M e^{-\beta(U_L - U_H)} \right\rangle_H}{\left\langle e^{-\beta(U_L - U_H)} \right\rangle_H}$$

O Take $M \equiv \delta[u - (U_L - U_H)]$

$$\left\langle \delta \right\rangle_{L} = \frac{\left\langle \delta e^{-\beta(U_{L}-U_{H})} \right\rangle_{H}}{\left\langle e^{-\beta(U_{L}-U_{H})} \right\rangle_{H}}$$

O Previously we derived this result

$$\langle M \rangle_L = \frac{\left\langle M e^{-\beta(U_L - U_H)} \right\rangle_H}{\left\langle e^{-\beta(U_L - U_H)} \right\rangle_H}$$

O Take $M \equiv \delta[u - (U_L - U_H)]$

This is
$$\langle \delta \rangle_L = \frac{\left\langle \delta e^{-\beta (U_L - U_H)} \right\rangle_H}{\left\langle e^{-\beta (U_L - U_H)} \right\rangle_H}$$

O Use definitions of p_H and p_L

$$p_L(u) =$$

O Previously we derived this result

$$\langle M \rangle_L = \frac{\left\langle M e^{-\beta(U_L - U_H)} \right\rangle_H}{\left\langle e^{-\beta(U_L - U_H)} \right\rangle_H}$$

O Take M = $\delta[u - (U_L - U_H)]$ $\langle \delta \rangle_L = \frac{\langle \delta e^{-\beta (U_L - U_H)} \rangle_H}{\langle e^{-\beta (U_L - U_H)} \rangle_H}$

This is u; the delta function lets us take it outside the average

O Use definitions of p_H and p_L

$$p_L(u) = \frac{p_H(u)e^{-\beta u}}{2}$$

O Previously we derived this result

$$\langle M \rangle_L = \frac{\left\langle M e^{-\beta(U_L - U_H)} \right\rangle_H}{\left\langle e^{-\beta(U_L - U_H)} \right\rangle_H}$$

O Take $M \equiv \delta[u - (U_L - U_H)]$

$$\langle \delta \rangle_L = \frac{\left\langle \delta e^{-\beta(U_L - U_H)} \right\rangle_H}{\left\langle e^{-\beta(U_L - U_H)} \right\rangle_H}$$
 This is the free-energy difference

O Use definitions of p_H and p_L

$$p_L(u) = \frac{p_H(u)e^{-\beta u}}{e^{-\beta\Delta A}}$$

O Previously we derived this result

$$\langle M \rangle_L = \frac{\left\langle M e^{-\beta(U_L - U_H)} \right\rangle_H}{\left\langle e^{-\beta(U_L - U_H)} \right\rangle_H}$$

O Take $M \equiv \delta[u - (U_L - U_H)]$

$$\left\langle \delta \right\rangle_{L} = \frac{\left\langle \delta e^{-\beta (U_{L} - U_{H})} \right\rangle_{H}}{\left\langle e^{-\beta (U_{L} - U_{H})} \right\rangle_{H}}$$

O Use definitions of p_H and p_L

$$p_L(u) = \frac{p_H(u)e^{-\beta u}}{e^{-\beta\Delta A}} \quad \cdot$$

rearrange

 $p_L(u)e^{-\beta\Delta A} = p_H(u)e^{-\beta u}$



• Examine them later; present interest is using distributions to understand FEP performance

Accuracy and Precision

- O Consider performance of FEP calculations from two perspectives
- **O** Precision
 - reproducibility of the result
- O Accuracy
 - correctness of the result
- O Example
 - hard-sphere deletion calculation good precision terrible accuracy



Tail Contributions in FEP Calculations O Examine contributions to FEP averages

Generalized insertion

 $e^{-\beta\Delta A} = \int du \, e^{-\beta u} \, p_H(u)$



$$e^{+\beta\Delta A} = \int du \, e^{+\beta u} \, p_L(u)$$



Inaccuracy in FEP Calculations 1.

O Main source of inaccuracy is inadequate sampling of tails



O Model inaccuracy by assuming all error is due to missing tail contribution $e^{-\Delta A_H} - e^{-\Delta A_{exact}} = \int_{-\infty}^{u_H} p_H(u)e^{-\beta u} du = \begin{bmatrix} e^{-\beta \Delta A} \int_{-\infty}^{u_H} p_L(u) du \\ e^{-\beta \Delta A} \int_{-\infty}^{u_H} p_L(u) du \end{bmatrix}$ Inaccuracy in each method is given by area under $e^{+\beta \Delta A} \int_{-\infty}^{\infty} p_H(u) du$ curve for other method

 u_L

Inaccuracy in FEP Calculations 2.

$$e^{-\Delta A_{H}} - e^{-\Delta A_{exact}} = \int_{u_{L}}^{u_{H}} p_{H}(u)e^{-\beta u}du = \begin{bmatrix} e^{-\beta\Delta A}\int_{u_{L}}^{u_{H}} p_{L}(u)du \\ e^{+\Delta A_{L}} - e^{+\Delta A_{exact}} = \int_{u_{L}}^{\infty} p_{L}(u)e^{+\beta u}du = \begin{bmatrix} e^{-\beta\Delta A}\int_{u_{L}}^{u_{H}} p_{L}(u)du \\ e^{+\beta\Delta A}\int_{u_{L}}^{\infty} p_{H}(u)du \\ u_{L} \end{bmatrix}$$

O Missing tail contributions

Inaccuracy in each method is given by area under curve for other method



O Relative inaccuracy

e

$$\delta_{H} = \frac{e^{-\Delta A_{sim,H}} - e^{-\Delta A_{exact}}}{e^{-\Delta A_{exact}}} = \int_{-\infty}^{u_{H}} p_{L} du \quad \Delta A_{sim,H} - \Delta A_{exact} > 0 \quad \text{Insertion overestimates}$$

$$\delta_{L} = \frac{e^{-\Delta A_{sim,L}} - e^{-\Delta A_{exact}}}{e^{-\Delta A_{exact}}} = -\int_{u_{L}}^{\infty} p_{H} du \quad \Delta A_{sim,L} - \Delta A_{exact} < 0 \quad \text{Deletion underestimates}$$

Asymmetry of the Inaccuracy 1.

• The opposite tendency of the insertion/deletion inaccuracy leads to statements like these

- "The forward and reverse [inaccuracy] should be of the same magnitude and opposite sign" J. Phys. Chem., 98, 1487-1493,1999
- "The free energy change was taken as the average of the forward and reverse free energies." J Comp. Chem., 20, 499-510, 1999
- O Remember the asymmetry of the hard-sphere insertion/deletion methods
 - for insertion, $e^{-\beta\mu}$ is zero until a non-overlap is completed
 - for deletion $e^{+\beta\mu}$ is always unity
 - averaging the insertion and deletion μ 's would be bad

Asymmetry of the Inaccuracy 2.

- $O p_H$ and p_L have different variances
- O Reference with broader distribution gives more accurate result
- O Large entropy reference has larger variance hence gives more accurate result

Improvement of accuracies as length of simulation grows



O Insertion is more reliable than deletion

Predicting Inaccuracy

O Maximum likelihood analysis

- consider most likely outcome for simulation with length M
- O Need most likely values for u_H , u_L
- O Consider probability that largest deletion energy is some value, u*, after M attempted deletions



 $prob(u_L = u^*) = prob(u^* \text{ is sampled}) \times prob(u > u^* \text{ is never sampled})$

٦M

$$= p_L(u^*) \times \left[1 - \int_{u^*}^{\infty} p_L(u) du \right]$$

Similar formula derived for insertion

O Maximize with respect to u*

$$\frac{\partial \ln p_H(u)}{\partial u}\bigg|_{u_H} = Mp_H(u_H) - \beta$$
$$\frac{\partial \ln p_L(u)}{\partial u}\bigg|_{u_L} = -Mp_L(u_L) - \beta$$

Testing Inaccuracy Model

O MC Simulation

- *NVT*
- $(N-1) LJ + 1 HS \longleftrightarrow NLJ$
- $HS \ diameter = 0.8$
- $T = 2.0; \ \rho = 0.9$
- simulation repeats up to 200 runs



Knowing Your Inaccuracy

- O How can the accuracy of a simulation result be assessed if the simulation is inaccurate?
- O Compare to precision calculation where simulation data (variance) are used to provide confidence limits
- O Consider most-likely inaccuracy for HS insertion

 $\delta_{\Delta A} = \left(2Me^{\Delta S}\right)^{-1}$

Insertion only ($\Delta S < 0$)

- **O** Postulate $\delta_{\Delta A} \sim (Me^{\Delta S})^{-1}$ for continuous distributions
 - evaluate ΔA accuracy using simulation ΔS

O But simulation gives 'incorrect' ΔS

- generally, simulation $\Delta S < true \Delta S (e^{-\Delta S(sim)} > e^{-\Delta S(true)})$
- thus 'incorrect' ΔS indicates larger error
- safe estimate of inaccuracy
- gives (probabilistic) upper bound of ΔA inaccuracy

Test of Postulated Form 1.

- *MC* simulations with various conditions
- repeat simulations for up to 100 independent runs
- very long simulation generates pseudo true ΔA
- calculate entropy change, error-bar, inaccuracy etc.

1010101100	density	temperature	$\Delta S/k$
$(N-1)LJ + 1$ (LJ with $\alpha = 0.9$)	0.9	2.0	-1.702
$(N-1)LJ + 1$ (LJ with $\alpha = 0.72$)	0.9	2.0	-4.250
$(N-1)LJ + 1$ (LJ with $\alpha = 0.65$)	0.8	1.0	-4.450
$(N-1)LJ + 1$ (LJ with $\alpha = 0.7$)	0.9	1.0	-5.799
(N-1) LJ	0.8	1.0	-8.743
(<i>N</i> -1)LJ + 1 (soft with $\alpha = 0.3$)	0.9	1.0	-9.504
(N-1) LJ	0.9	1.0	-12.179
	$(N-1)LJ + 1 (LJ \text{ with } \alpha = 0.9)$ $(N-1)LJ + 1 (LJ \text{ with } \alpha = 0.72)$ $(N-1)LJ + 1 (LJ \text{ with } \alpha = 0.65)$ $(N-1)LJ + 1 (LJ \text{ with } \alpha = 0.7)$ $(N-1)LJ$ $(N-1)LJ + 1 (\text{soft with } \alpha = 0.3)$ $(N-1)LJ$	$(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.9)$ 0.9 $(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.72)$ 0.9 $(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.65)$ 0.8 $(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.7)$ 0.9 $(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.3)$ 0.9 $(N-1)LJ + 1$ $(\text{soft with } \alpha = 0.3)$ 0.9 $(N-1)LJ + 1$ $(\text{soft with } \alpha = 0.3)$ 0.9	$(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.9)$ 0.9 2.0 $(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.72)$ 0.9 2.0 $(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.65)$ 0.8 1.0 $(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.7)$ 0.9 1.0 $(N-1)LJ + 1$ $(LJ \text{ with } \alpha = 0.7)$ 0.9 1.0 $(N-1)LJ + 1$ $(soft \text{ with } \alpha = 0.3)$ 0.9 1.0 $(N-1)LJ + 1$ $(soft \text{ with } \alpha = 0.3)$ 0.9 1.0



Test of Postulated Form 2.

- *MC* simulations with various conditions
- repeat simulations for up to 100 independent runs
- very long simulation generates pseudo true ΔA
- calculate entropy change, error-bar, inaccuracy etc.

$$\delta_{\Delta A} = \left(2Me^{\Delta S}\right)^{-1}$$

Appropriate group, perhaps incorrect exponent

Series	reference	density	temperature	$\Delta S/k$
1	$(N-1)LJ + 1$ (LJ with $\alpha = 0.9$)	0.9	2.0	-1.702
2	$(N-1)LJ + 1$ (LJ with $\alpha = 0.72$)	0.9	2.0	-4.250
3	$(N-1)LJ + 1$ (LJ with $\alpha = 0.65$)	0.8	1.0	-4.450
4	$(N-1)LJ + 1$ (LJ with $\alpha = 0.7$)	0.9	1.0	-5.799
5	(N-1) LJ	0.8	1.0	-8.743
6	$(N-1)$ LJ + 1 (soft with $\alpha = 0.3$)	0.9	1.0	-9.504
7	(N-1) LJ	0.9	1.0	-12.179
N = 108				



Precision of FEP Calculations 1.

O Consider *L* simulations, each doing *M* insertions 1,2,3,4,5,...,M 1,2,3,4,5,...,M. *L times*

1,2,3,4,5,...,M

O Each M-length run gives a value for ΔA

• Variance of these averages for the L runs describes the precision of the calculation



$$\sigma_{\Delta A}^2 \approx e^{\pm \beta \Delta A} \sum p_i (1 - p_i) e^{\pm 2\beta u_i}$$

Return to ()continuum formulation, rewrite

$$\left(M\sigma^{2}\right)_{del} = \exp(-\beta\Delta A)\int_{-\infty}^{\infty} p_{H}(u)e^{+\beta u}du$$
$$\left(M\sigma^{2}\right)_{ins} = \exp(+\beta\Delta A)\int_{-\infty}^{\infty} p_{L}(u)e^{-\beta u}du$$

Note that exponents have signs opposite those for averages

Precision of FEP Calculations 3.

O Decompose into entropic and energetic contributions

• focus on insertion form

$$(M\sigma^2)_{ins} = e^{-\Delta S/k} \int_{-\infty}^{\infty} du \ p_L(u) e^{-\beta(u-\Delta U)}$$

• expand

$$\left(M\sigma^2\right)_{ins} = e^{-\Delta S/k} \int_{-\infty}^{\infty} du \, p_L(u) \left[1 - \beta(u - \Delta U) + \frac{1}{2}\beta^2(u - \Delta U)^2 + \dots\right]$$

• finally

•

$$\left(M\sigma^2\right)_{ins} = e^{-\Delta S/k} \left(1 + \frac{1}{2}\beta^2 \hat{\sigma}_{\Delta U}^2\right) \equiv \zeta e^{-\Delta S/k}$$

entropy difference is key

Variance of energy in L system (independent of M); O(1) quantity

Optimal Staging

O Apply precision model to optimize choice of intermediate in staged insertion

• how best to define U_W ? $e^{-\beta\Delta(A_L - A_H)} = \langle e^{-(U_w - U_H)} \rangle_H \langle e^{-\beta(U_L - U_w)} \rangle_W$

O Overall variance is the sum of variances of all stagesO Choose W:

• minimize
$$(M\sigma^2)_{tot} = \sum_i \zeta_i \exp(-\Delta S_i/k)$$

• subject to
$$\sum \Delta S_i = \Delta S_{to}$$

- obtain $\Delta(\Delta S)_{ij} \equiv \Delta S_j \Delta S_i = k \ln(\zeta_j / \zeta_i)$
- ζ_j/ζ_i : order of unity

O Heuristic: $\Delta(\Delta S) = 0$

- equal entropy difference
- compare to unjustified rule-of-thumb equal free-energy difference $\Delta(\Delta A/k) = 0$
- new rule greatly improves the precision



Example Application



<u>System H</u> N-1 LJ particles System W N-1 Lennard-Jones particles 1 Hard sphere of diameter α

System L N LJ particles

O Optimize with respect to intermediate-HS diameter α



Summary

- FEP energy distributions provide detailed information regarding free-energy differences
- O Relation between insertion and deletion distribution can be used to measure free-energy differences
- O Distributions can be used to understand precision and accuracy of FEP calculations
- O Insertion usually gives too-high value, deletion too low
 - but not equally so; deletion is much worse

O Formulated way to estimate inaccuracy using inaccurate data

- O Both accuracy and precision strongly depend on entropy difference between states
- O Can use precision analysis to optimize staged insertions